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Inventor:

KOPISCHKE STEPHAN (DE)

Applicant:

VOLKSWAGENWERK AG (DE)

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Abstract of DE19933732

The parking/unparking aid has at least one distance measurement device for detecting objects in the area round a vehicle, a steering angle sensor, a computer unit for evaluating data from the distance and steering angle sensors and a signalling device driven by the computer unit to influence the vehicle driver. The computer unit monitors the parking/unparking process based on the detected data and checks whether there is an object in the pre-computed driving channel. The signalling device sends a free signal if there is no obstruction to driving. An Independent claim is also included for a method of controlling parking and unparking processes for a motor vehicle.

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